Beneficial performance from IBRs for provision of bulk power system services

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Evolving system needs expected from Inverter Based Resources (IBRs)

Power System

Past:

SG dominated system

Present: Increased penetration of IBRs

Future: IBR dominated system

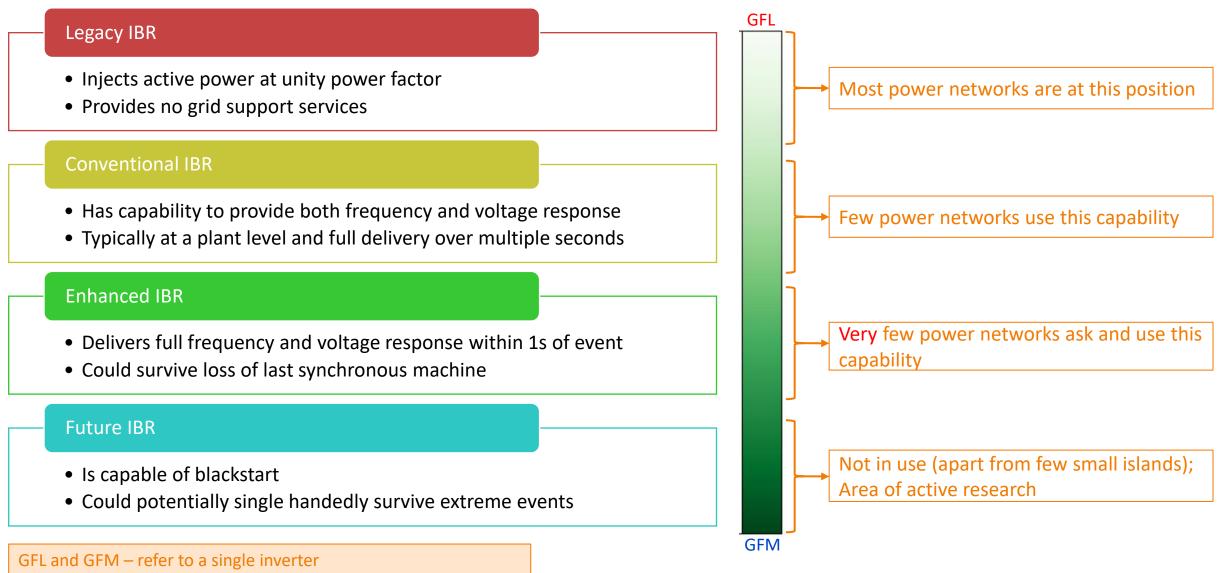
System needs from IBR

Unity power factor, minimal fault ride-through ...

Automatic voltage control, frequency response, V/F ridethrough ...

Without relying on SGs, provide the above services and more (fast frequency response, maintain system stability...) Moving toward an inverter dominated power system, IBRs will gradually substitute SGs in providing grid services and ensuring grid reliability

Technology terminology in this presentation



IBR – refers to entire plant containing numerous inverters

Services from IBRs

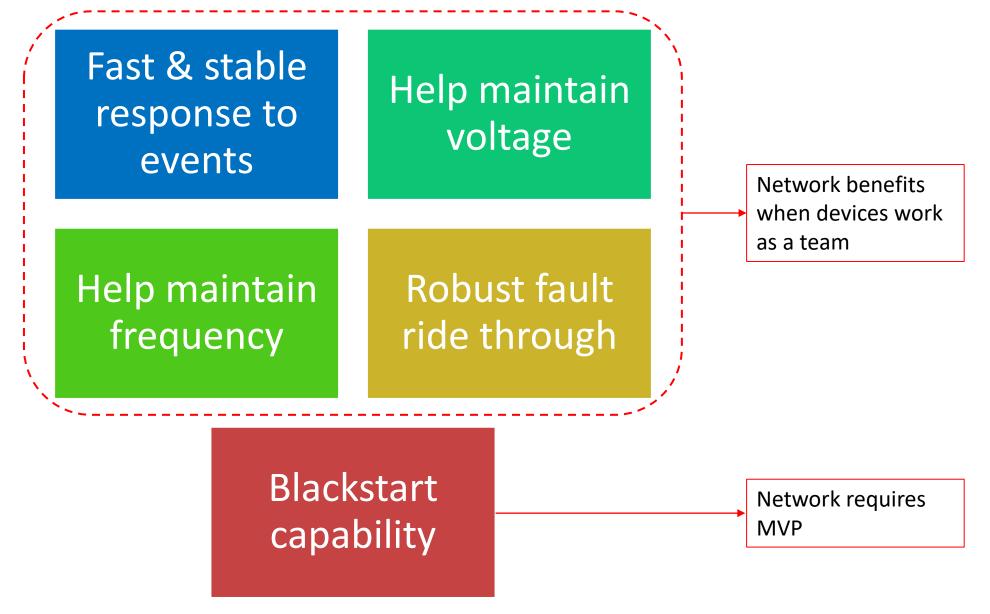
- Gigawatts (GWs) of IBRs in the present power network, whose capability is underutilized
- Hundreds of GWs of IBRs presently in the interconnection queue for whom, utilization/delivery of full capability is either not required, or is optional (market product).
- Underutilization of capability today can lead to increased burden and timeline of capability provision on future IBR.
- Power system operation is a team sport
 - Improved reliability when each player contributes a little, in a beneficial manner
 - Entire burden cannot (and should not) fall on the MVP*

Subsequent sections of presentation discusses concepts of how each IBR could contribute in a beneficial manner

*Most Valuable Player

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Categories of services from IBRs

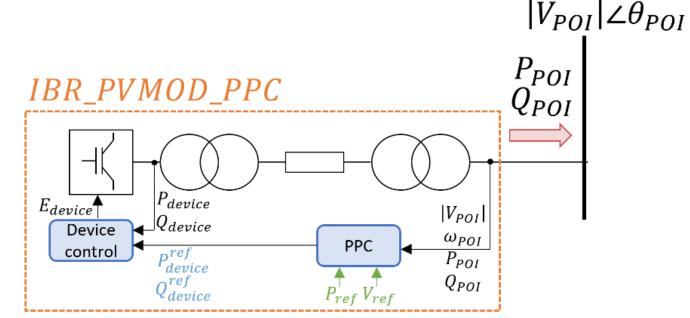


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Hierarchy of delivery of services in conventional IBR

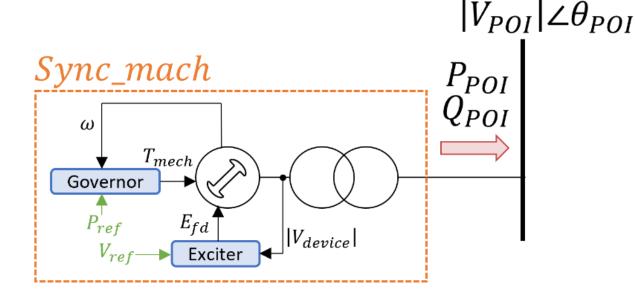
- Conventional IBR plant has two hierarchy of control
 - plant controller responsible for power, voltage, and frequency control of the plant
 - inverter/turbine controller responsible for active and reactive power control



- Plant level controller incorporates principles of droop for voltage and frequency control
 - Typically slow control
- Inverter level controller may have open or closed loop power control
 - Generally fast control

Hierarchy of delivery of services in synchronous machine

- Conventional synchronous machine has one hierarchy of control
 - Machine level controllers responsible for frequency and voltage control
- No plant level control

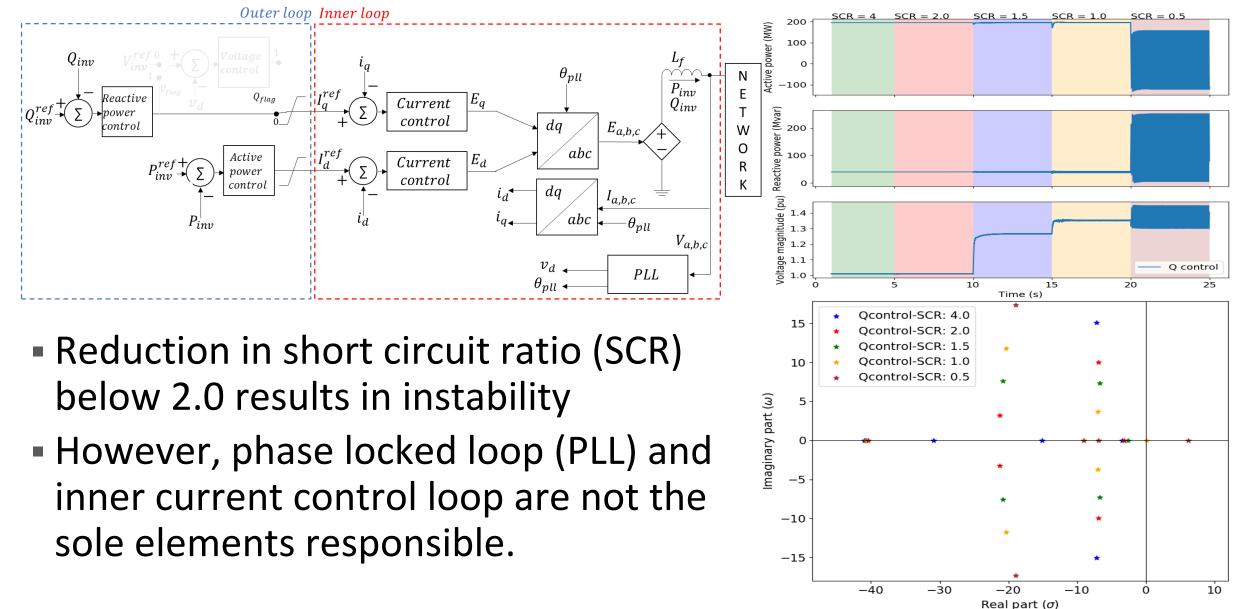


 Device (machine) level control is fast in modern synchronous machine plants

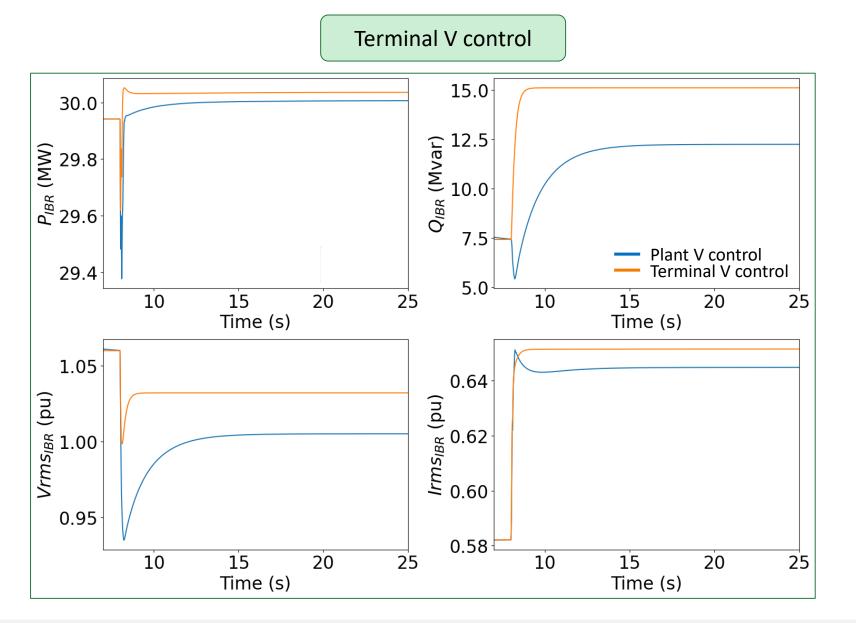
Difference in hierarchy of delivery of services plays a crucial role in determining improvement of system reliability

Fast Voltage Response

Conventional IBR and system strength reduction

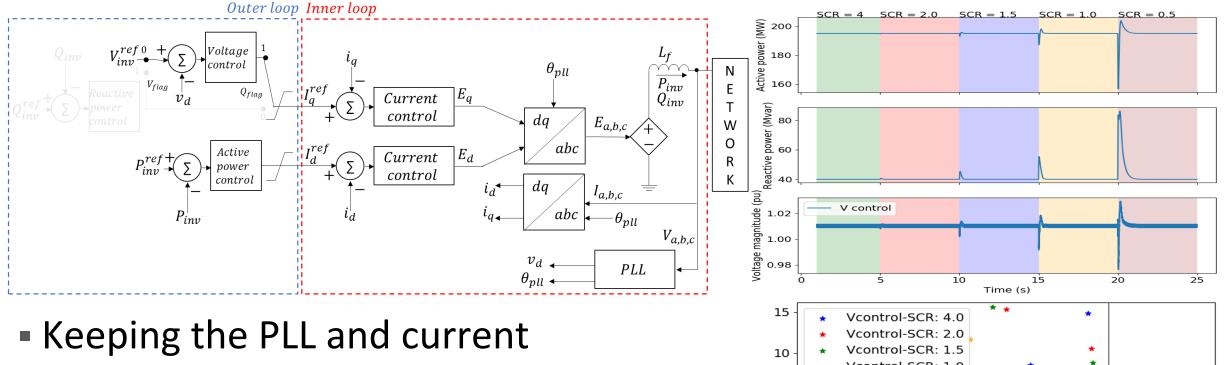


Bringing about fast voltage response at device level



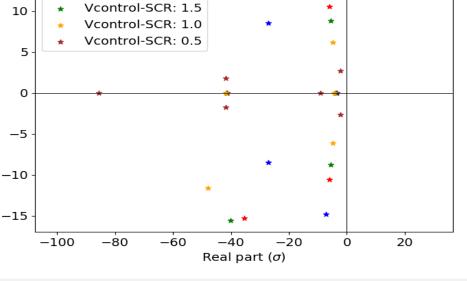
Plant level voltage control can be augmented with inverter level voltage control Could provide improved benefit with high IBR systems

Switching to fast inverter level voltage control

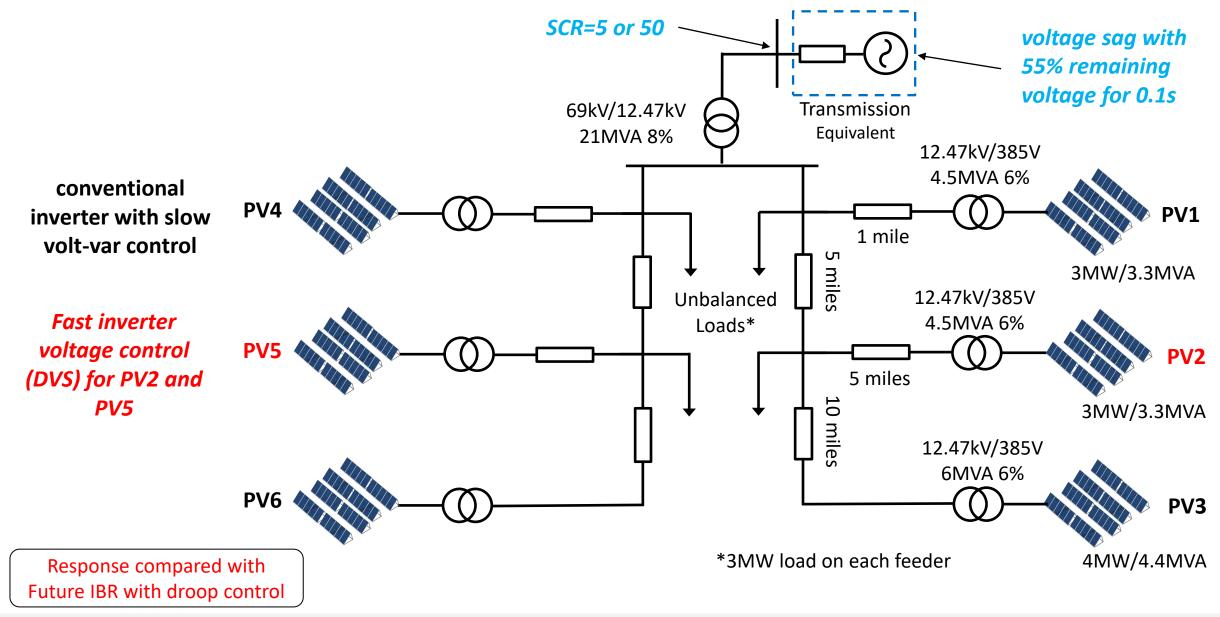


maginary part (ω)

- controller gains the same, switch to inverter level voltage control.
- From a small signal sense, the control is now stable even for SCR of 0.5!

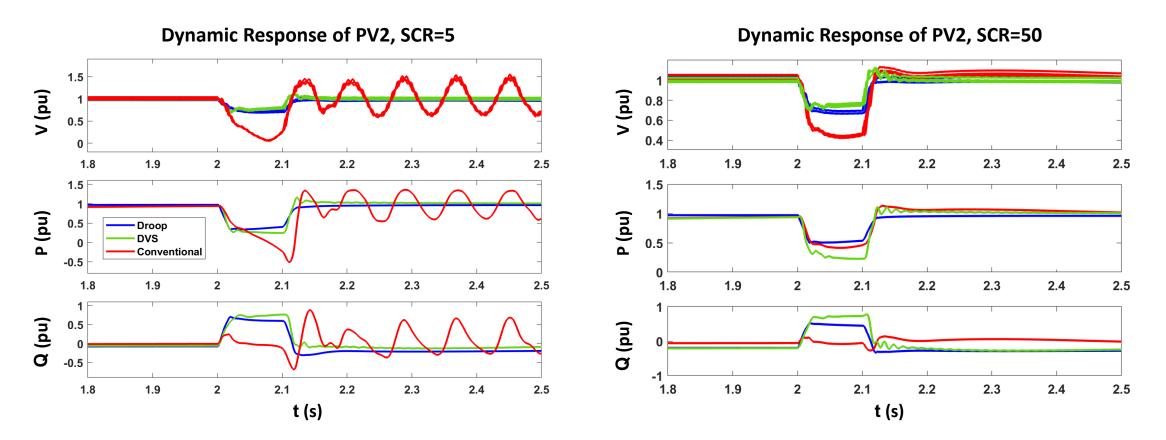


System level application example



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Performance comparison



Use of fast inverter level voltage control, could help improve the reliability of the network

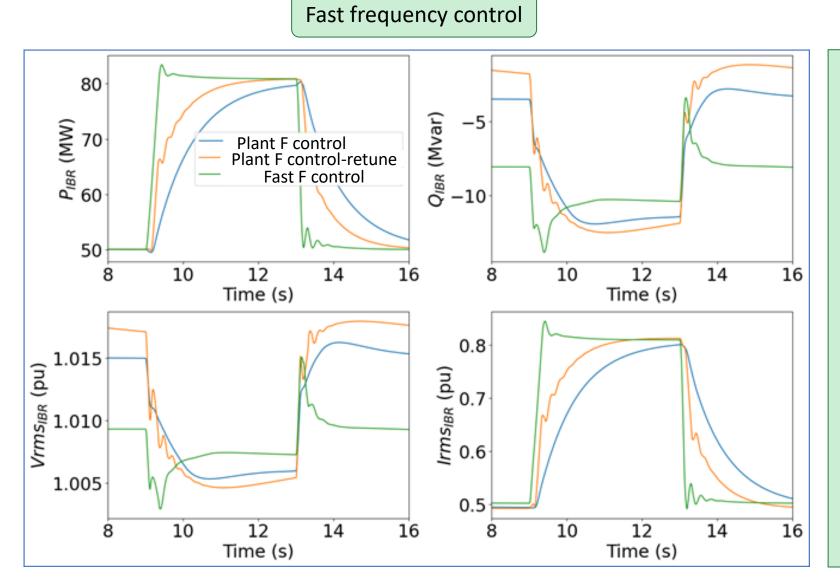
Note this is not to imply that future IBR technology may not be required

Interim takeaway

- Traditional hierarchy of inverter level reactive power control is a contributing factor to instability in low short circuit conditions
- Going to fast inverter level voltage control provides improved stability and reliability benefits
- To understand this from a power flow perspective:
 - Traditional inverter level reactive power control can be related to a PQ bus in power flow
 - Switching to inverter level voltage control can be related to a PV bus in power flow
 - Increased number of PV buses is beneficial from a power flow solution
 - A similar benefit is obtained in dynamic stability

Fast Frequency Response

Bringing about fast frequency response at device level



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 Plant level frequency control can be augmented with inverter level fast frequency control

 Could provide improved benefit with high IBR systems

Example requirements from around the world

National Grid UK

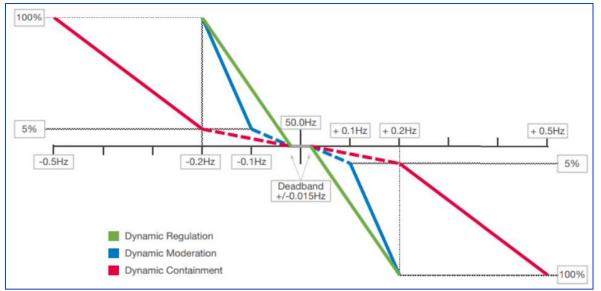


Figure source: https://www.nationalgrideso.com/document/276606/download

- Dynamic containment and dynamic moderation services to be delivered within 1s
- Piecewise droop with minimum value of 0.21%!!
- Expectation is to deliver a linear (and not switched) response

AEMO

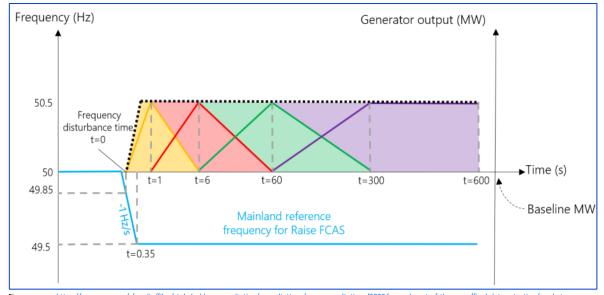


Figure source: https://aemo.com.au/-/media/files/stakeholder_consultation/consultations/nem-consultations/2022/amendment-of-the-mass/final-determination/marketancillary-services-specification---v80-effective-9-oct-2023.pdf?la=en______

- Very fast frequency control ancillary service to be delivered within 1s
- Minimum droop of 1.7%
- Expectation is to deliver a linear (and not switched) response

IEEE 2800 – 2022 has similar requirements for capability related to fast frequency response



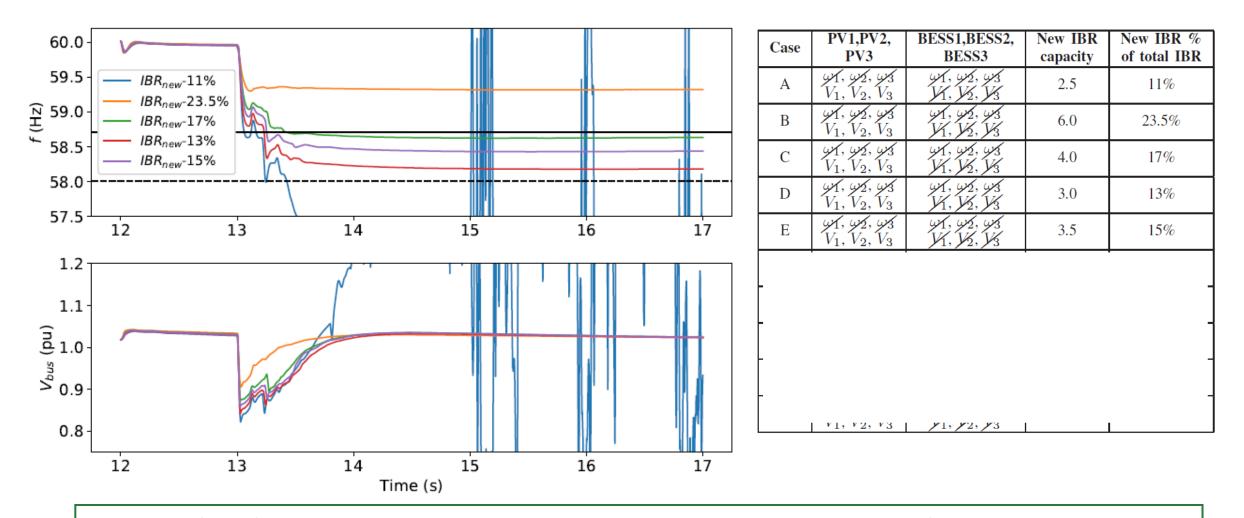
Example system level application

- Real island network with:
 - PV 8.25 MVA
 - BESS 8 MVA
 - DER 3.25 MVA
 - Load 2.9 MW
 - Sync condenser 2.75 MVA
- System contains ac coupled PV-BESS hybrid plants, and standalone PV and BESS plants.
- Total base case IBR MVA is 19.50 MVA
- Variety of scenarios based on ability of PV and BESS to provide fast frequency response at inverter level
- In addition, the size of a Future IBR is to be determined to maintain stability

| Case | PV1,PV2, PV3 | BESS1,BESS2, BESS3 | New IBR capacity | New IBR % of total IBR |
|------|--|--|---------------------|---------------------------|
| А | $\begin{array}{c} \omega_{1}, \omega_{2}, \omega_{3} \\ V_{1}, V_{2}, V_{3} \end{array}$ | $\mathcal{Y}_1, \mathcal{Y}_2, \mathcal{Y}_3$ $\mathcal{Y}_1, \mathcal{Y}_2, \mathcal{Y}_3$ | 2.5 | 11% |
| В | V_1, V_2, V_3 V_1, V_2, V_3 | y_1, y_2, y_3 y_1, y_2, y_3 | 6.0 | 23.5% |
| С | V_1, V_2, V_3 V_1, V_2, V_3 | $\mathcal{Y}_1, \mathcal{Y}_2, \mathcal{Y}_3$ $\mathcal{Y}_1, \mathcal{Y}_2, \mathcal{Y}_3$ | 4.0 | 17% |
| D | V_1, V_2, V_3 V_1, V_2, V_3 | | 3.0 | 13% |
| Е | V_1, V_2, V_3 V_1, V_2, V_3 | | 3.5 | 15% |
| F | $ \begin{array}{c} \omega_1, \omega_2, \omega_3 \\ V_1, V_2, V_3 \end{array} $ | $\omega_1, \omega_2, \omega_3$ $\gamma_1, \gamma_2, \gamma_3$ | 2.5 | 11% |
| G | $\begin{array}{c} \omega_1, \omega_2, \omega_3 \\ V_1, V_2, V_3 \end{array}$ | $\omega_1, \omega_2, \omega_3$ V_1, V_2, V_3 | 1.5 | 7% |
| Н | $ \begin{array}{c} \omega_1, \omega_2, \omega_3 \\ V_1, V_2, V_3 \end{array} $ | $\omega_1, \omega_2, \omega_3$ V_1, V_2, V_3 | 1.0 | 5% |
| J | V_1, V_2, V_3 V_1, V_2, V_3 | $\omega_1, \omega_2, \omega_3$ V_1, V_2, V_3 | 1.5 | 7% |
| K | V_1, V_2, V_3 V_1, V_2, V_3 | | 2.5 | 11% |

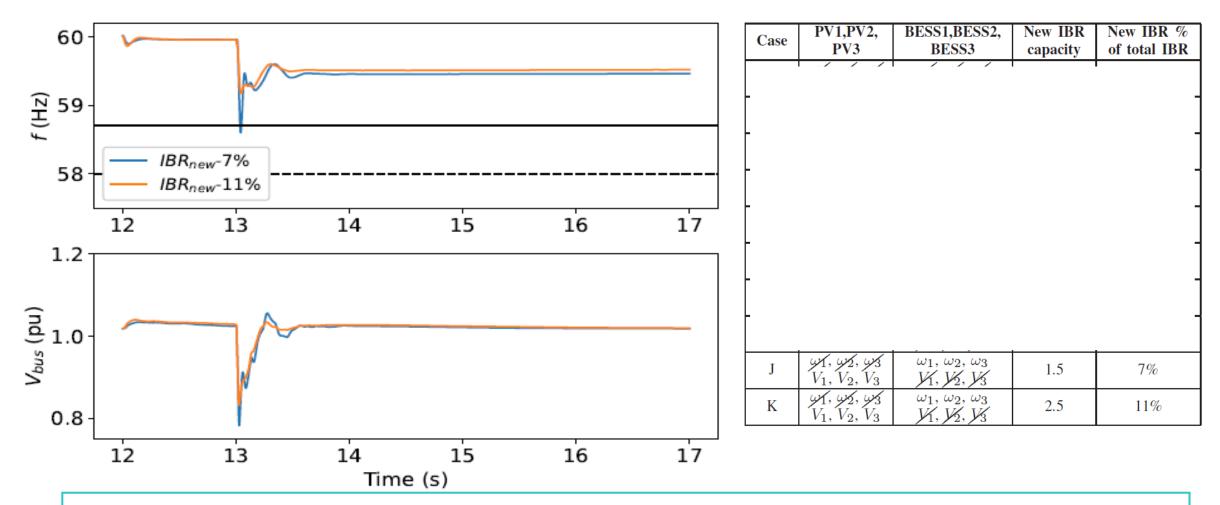
Note: here fast terminal voltage control is not considered

Scenario results



 When fast frequency response is not utilized, new Future IBR of around 25% is needed for system to be reliable

Scenario results



 When fast frequency response of only BESS is used, new Future IBR of around 11% is needed for system to be reliable

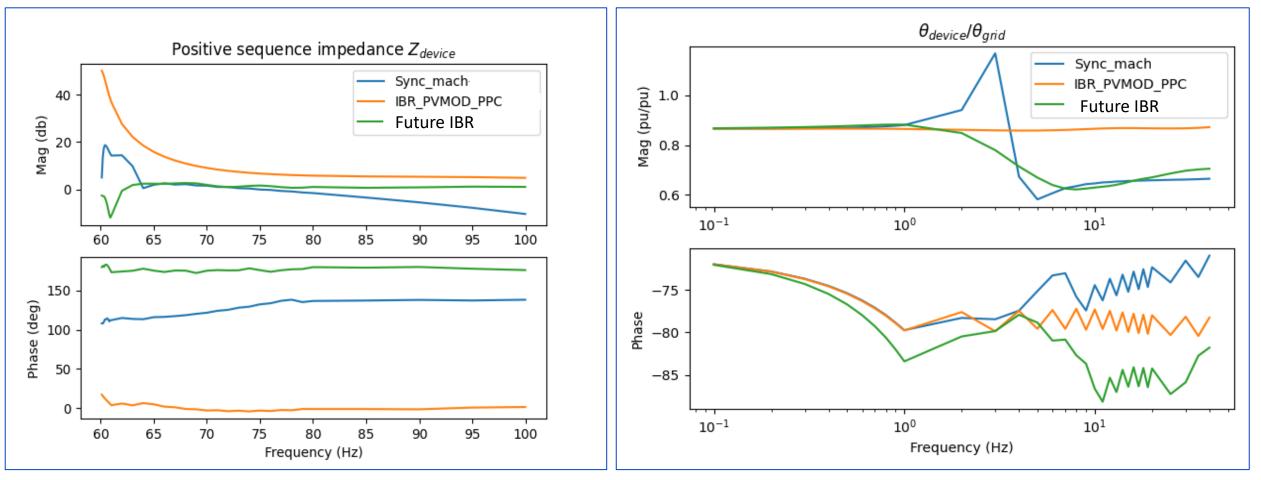
Interim takeaway

 Going to fast inverter level frequency control could provide improved stability and reliability benefits

- Needs to be carefully evaluated and verified as it could cause control interactions if not designed appropriately.
 - The more resources that provide this response, the lesser incremental amount will each resource need to provide
 - This reduced burden on each resource can help improve stability

Stability and damping

Criteria for stability and damping



- Threshold for damping ratio are useful, but may have limitations regarding guarantees in a large network
- Frequency domain criteria is gaining more traction but still an open research topic to verify if criteria can be generalized
 Different flavors of such criteria across various stakeholders. To be harmonized

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Blackstart and system restoration

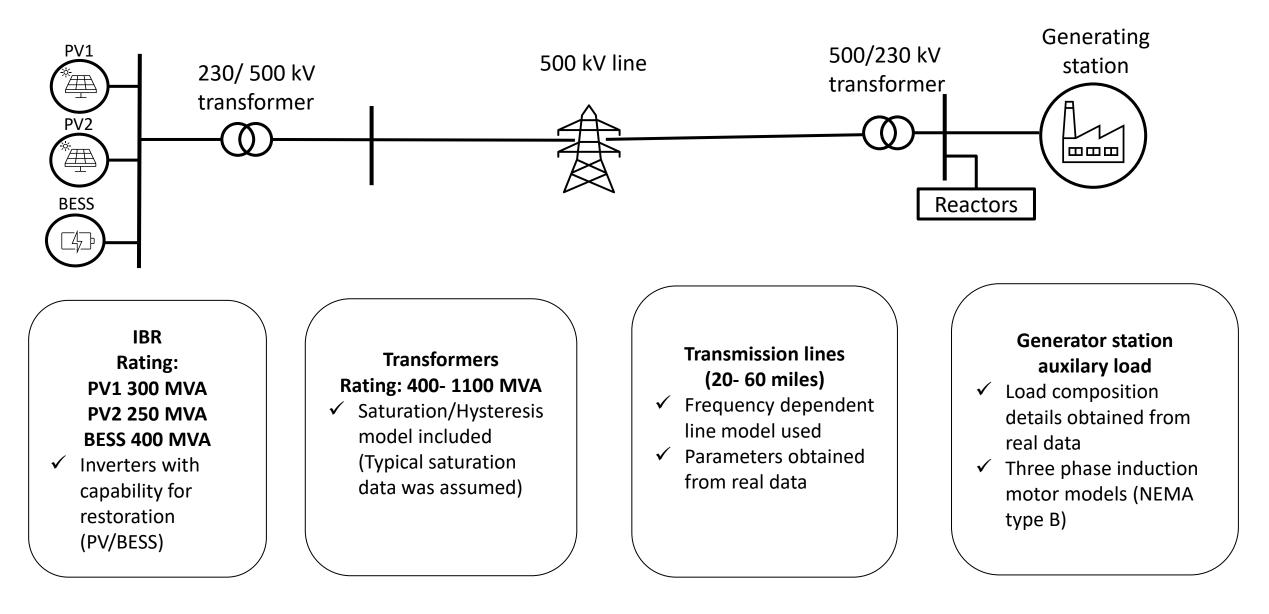
Objective

Determine the capability of IBR to meet future needs and provide services related to blackstart and system restoration

- Study carried out on real-world network.
- The cranking path of the network modeled using actual parameters to closely replicate practical conditions
- Evaluate ability of inverter-based resources (IBRs) to successfully energize transformers, transmission lines, and pick up load/generation sources
- Study impact of limited availability of IBR resources on system restoration
- Sensitivity studies to understand the impact of transformer saturation and hysteresis



Cranking path of the network for restoration



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Methodology and objectives that were achieved

| Detaile collection different co in the cra | n of the mponents | | BESS/PV created blackstart ca | with | | Development o frequency depend line model and validated the mod using real data | ent Jel | detaile genera with | elopment of ed model of a ating station three phase motors | | Study the impact of remnant flux/ saturation parameters of transformers |
|---|--|------------------------|-------------------------------------|---------------------------------|--|---|---|--------------------------------------|--|----------------|--|
| Data Ga | othering | | BESS/P\ Mod Develop | lel | | Development Frequency Dependent lin model | | mode | niled load ling of the ting station | | EMT transformer energization studies |
| | Highligh impact of l resource voltage/f | imited IBR e on the | | advanta starting the netw | astrated the ages of soft a portion o vork at lowe age level | t of | Established t are able to s inrush cur without exc voltage/free limits | support rents eeding quency | | able voltag | shed IBRs are to controls ge/frequency thin limits |
| | Impact o IBR reso the rest proc | urce on oration | - | soft er to re | ct of using nergizatio store the king path | n 🛑 | EMT simul load pie | | | the e | mulation of nergization storation path |

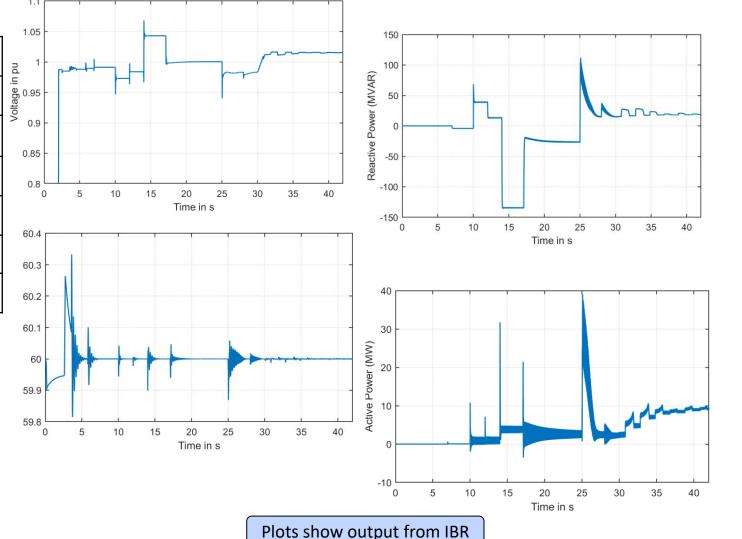
Objective achieved Methodology

Overview of restoration from IBR to motor pickup

| | | _ |
|------------------------------------|---------------|------------|
| Sequence | Time | nd |
| Synchronize the IBR plants | 2-5 seconds | Voltage in |
| Energize the 230/500kV transformer | 10-11 seconds | > |
| Energize 500kV Line | 12-15 seconds | |
| Energize the reactors | 17-20 seconds | |
| Energize the 500/230kV transformer | 25-28 seconds | |
| Energize motors sequentially | 31-45 seconds | |

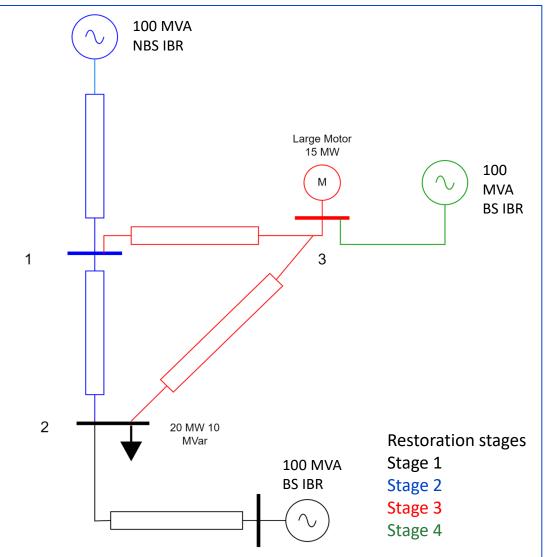
Key Takeaways

- No instability in voltage/frequency is observed under these conditions
- Generator auxilary load was successfully energized
- Transmission line generates high levels of charging current to be absorbed by IBR (~3Mvar/Mile)

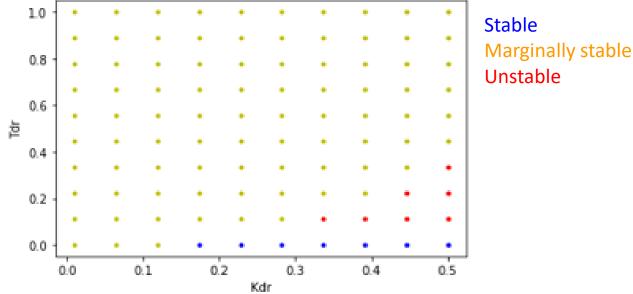


Oscillatory behavior observed in active power measurements is a result of non-linear magnetization characteristics of the network and should be considered carefully when evaluating IBR capability for restoration

Importance of control stability during restoration



NBS – Non blackstart BS – Blackstart



- Early restoration stages typically have lightly loaded network
- Control interactions between different types of inverter control and load dynamics an occur
- These interactions may not be visible when setting up control of an IBR in a SMIB setup



Summary



Takeaways

- Maintaining reliability in the power network is a team sport
 - If each device (player) contributes a bit, the benefits can be tremendous

- Increased utilization of fast inverter level voltage and frequency control can improve reliability
 - A lot of capability from IBRs is being left under utilized
- Simultaneously, adoption of newer forms of robust IBR control is important, after verifying their performance

ESIG Services Task Force

- Objective of the Task Force
 - Identify various services that can be delivered by Enhanced IBR and Future IBR
 - Quantify magnitude of service required by the power network
 - Evaluate if type and magnitude of service is generalizable across networks

 Send a note to Ryan Willis (<u>ryan@esig.energy</u>) and Julia Matevosyan (<u>julia@esig.energy</u>) if interested in participating

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